# Repeated Bidding with Dynamic Value 

Benjamin Heymann, Alexandre Gilotte and Rémi Chan-Renous Journée des rencontres ENSAE-ENSAI, 12-13 septembre 2023

Criteo AI Lab and Fairplay

Dynamic Value: motivation and challenge

## Display Advertising



Figure 1: Display advertising allows the monetizing of publisher content on the internet.

## Textbook solution to the bidding problem ${ }^{1}$

## Bid $=$ value

${ }^{1}$ In second price auctions, it is optimal to bid the value

## Textbook solution to the bidding problem ${ }^{2}$


${ }^{2}$ In second price auctions, it is optimal to bid the valuation of the display

## Dynamic value


???
$\left(^{*}{ }^{*}\right)^{\text {a }}$

Bid $=$ value for the display opportunity

## A possible approach

The optimal bid satisfies

$$
b^{\star}=\underset{b}{\arg \max } \mathbb{E}[D \cdot(V-\text { Cost }) \mid \text { Bid }=b]
$$

with
$\underbrace{V}_{\text {display valuation }}=\underbrace{\alpha}_{\text {constant factor }} \cdot \Delta S-\Delta F \operatorname{Cost}$

$$
\begin{aligned}
D & =1 \quad \text { if we win the auction } \\
\Delta S & =\operatorname{Pr}(\text { conversion } \mid D=1)-\operatorname{Pr}(\text { conversion } \mid D=0)
\end{aligned}
$$

$$
\Delta F \text { Cost }=\text { "How much the display changes future cost" }
$$

Martin Bompaire, Alexandre Gilotte, and BH. "Causal Models for Real Time Bidding with Repeated User Interactions"

Observe that $\Delta F$ Cost and $\Delta S$ are

1. functions of the optimal bid
2. counterfactual quantities
$\rightarrow$ Solving an analytic example would be a step in the right direction

## Contributions

- We analyze the case value $=k(\tau)$, and provide an algorithm to compute the optimal bidding strategy.
- We observe that empirically, there are constant shading factors that perform very well.

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## Dynamic value



## Model: $(\mu, k, q)$

- $\tau$ : age of the last won auction
- $\mu$ : intensity of the auction arrivals
- $k(\tau)$ : value of the item for the bidder (non-decreasing and bounded)
- $q(b)$ : win rate probability that the buyer wins with a bid equal to $b$
- $p(b)$ average payment of the user when bidding $b$ (second price auction)
- $\gamma$ : discount rate
$\rightarrow$ Markov Chain with continuous time state and action.


## Continuation function

For a bidding function $b: \tau \longrightarrow b(\tau) \in \mathbb{R}^{+}$, the expectation of the bidder's future payoff when the state is $\tau$, is

$$
V_{b}(\tau) \stackrel{\text { def }}{=} \mathbb{E} \sum_{i=1}^{\infty} e^{-\gamma T_{i}} \underbrace{\left(k\left(\tau\left(T_{i}\right)\right)-C_{i}\right) 1\left\{b\left(\tau\left(T_{i}\right)\right)>C_{i}\right\}}_{\text {auction } i \text { payoff }} .
$$

where $T_{1}, T_{2} \ldots T_{n} \ldots$, are times of the next auctions, $C_{1} \ldots C_{n} \ldots$ the competition at these times.

$$
\underbrace{V^{\star}(\tau)}_{\text {Bellman value }} \stackrel{\text { def }}{=} \sup _{b \in \mathcal{B}} V_{b}(\tau) .
$$

## Dynamic programming

## Lemma

We have the relation

$$
V_{t}^{\star}=\int_{0}^{+\infty} \mu e^{-(\mu+\gamma) t}\left(\pi\left(k_{t}+V_{0}^{\star}-V_{t}^{\star}\right)+V_{t}^{\star}\right) \mathrm{d} t
$$

where

$$
\begin{aligned}
U(v, b) & =q(b) \cdot v-p(b) \quad(=\text { static payoff }) \\
\pi(v) & =U(v, v) \quad(=\text { static optimal payoff })
\end{aligned}
$$

Moreover,

$$
b^{\star}(\tau)=\max (0 ; \underbrace{k(\tau)+V^{\star}(0)-V^{\star}(\tau)}_{\text {incremental gain from winning the auction }}) .
$$

## ODE Reformulation

Lemma
Set $\Phi(t, v, \lambda)=\gamma v-\mu \pi\left(k_{t}+\lambda-v\right)$. The value function $V^{\star}$ is the solution of the ordinary differential equation

$$
\left\{\begin{array}{l}
\dot{Y}_{t}=\Phi\left(t, Y_{t}, y_{0}\right)  \tag{0}\\
Y_{0}=y_{0}
\end{array}\right.
$$

for some $y_{0} \in \mathbb{R}_{+}$.

It should be noted that parameter $y_{0}$ is not given.

## Sufficient condition for monotony of $b^{\star}$

Theorem
If $k$ is concave, then $b^{\star}$ is increasing with $\tau$, and strictly increasing on any interval where $k$ strictly increases.

## Counter-example



## Main result

By the Cauchy-Lipschitz Theorem, the solution of the ordinary differential equation

$$
\left\{\begin{array}{l}
\dot{Y}_{t}=\Phi\left(t, Y_{t}, \lambda\right)  \tag{0}\\
Y_{0}=v_{0}
\end{array}\right.
$$

admits a unique maximal solution $Z^{y_{0}, \lambda}: t \rightarrow Z^{y_{0}, \lambda}(t)$ for any $y_{0}>0$ and $\lambda>0$. We set $Z^{v}(t)=Z^{v, v}(t)$.

## Lemma

Suppose $q$ continuous. The value $V_{0}^{\star}$ is the unique $v$ for which $\lim _{t \rightarrow+\infty} Z^{\vee}(t)$ is finite.

## We can solve numerically using a dichotomy



Figure 2: An example of Algorithm run. In red is the output of the algorithm, in blue the iterates.

## What about shading policies? (1/2)



Figure 3: Ratio $V_{\alpha} / V^{*}$ as a function of $\alpha$ with $k_{\tau}=1-e^{-t}$ and $\mu=5$

## What about shading policies? (2/2)



Figure 4: Ratio $V_{\alpha} / V^{*}$ as a function of $\alpha$ with $\mu=5$ and $k(t)=1-1 / 1+t$

## Conclusion

[^0]
## Next

1. Non-asymptotic guaranties for the shading policies
2. More general dynamics
3. Online learning of the parameters

[^0]:    "In this end, it is not that bad, I just need to tweak $\alpha$ "
    (*_*)
    | |

    $$
    \text { Bid }=\underbrace{\alpha^{\#}}_{\text {tweaked factor }} \times \operatorname{Pr}(\text { Conversion } \mid \text { Display })
    $$

